DS 100/200: Principles and Techniques of Data Science

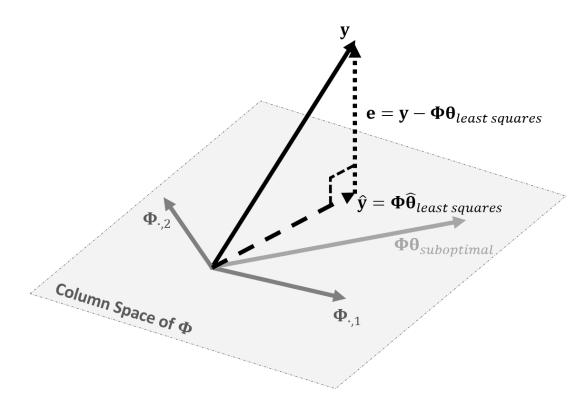
Date: March 15, 2019

Discussion #7

Name:

Geometry of Least Squares

 This diagram shows the geometry of 3 observations with 2 features. Φ₁ is the column vector of the three values for feature 1, and Φ₂ is the column vector of values for feature 2. We're fitting a model with parameters θ, a two-element vector, that determines a linear combination of the 2 features. A choice of θ gives fitted values for the 3 observations, and these fitted values are always in the column space of Φ. The observed y, a vector of the response values for the 3 observations, is not in the column space of Φ. The least-squares choice for θ is the one for which Φθ is closest to y. This diagram is analogous to a setting with more observations and more features.



(a) From the image above, what can we say about the residuals and the column space of Φ ? Write this mathematically and prove this statement using a calculus-based argument about minimizing the linear regression loss function.

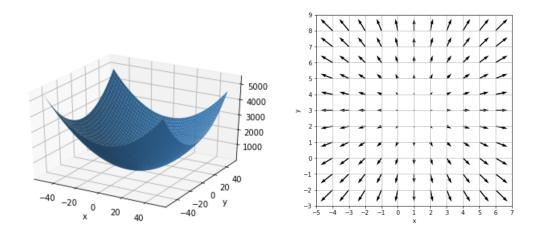
(b) Show that $\theta = (\Phi^T \Phi)^{-1} \Phi^T Y$. from the fact above for the least squares solution Φ .

- (c) Let Φ be a $n \times p$ design matrix with full column rank (the rank is equal to the number of columns). In this question, we will look at properties of matrix $H = \Phi(\Phi^T \Phi)^{-1} \Phi^T$ that appears in linear regression.
 - i. Recall for a vector space V that a projection $\mathbf{P}: V \to V$ is a linear transformation such that $\mathbf{P}^2 = \mathbf{P}$. Show that \mathbf{H} is a projection matrix.
 - ii. This is often called the "hat matrix" because it puts a hat on y, the observed responses used to train the linear model. Show that $Hy = \hat{y}$
 - iii. Show that M = I H is a projection matrix.
 - iv. Show that My results in the residuals of the linear model.

- v. Notice that the hat matrix is a function of our observations Φ rather than our response variable y. Intuitively, what do the values in our hat matrix represent? It might be helpful to write \hat{y}_i as a summation.
- (d) We can show that $rank(\Phi) = rank(\Phi^T \Phi)$ by showing that these two matrices have the same null space. List some reasons why Φ might not have full column rank, which would make $\Phi^T \Phi$ not invertible.

Gradients

2. On the left is a 3D plot of $f(x, y) = (x - 1)^2 + (y - 3)^2$. On the right is a plot of its gradient field. Note that the arrows show the relative magnitudes of the gradient vector.



- (a) Is this function convex? Make a visual argument—it doesn't have to be formal.
- (b) Superimpose a contour plot of this function for f(x, y) = 0, 1, 2, 3, 4, 5 onto the gradient field.
- (c) What do you notice about the relationship between the level curves and the gradient vectors?

- (d) From the visualization, what do you think is the minimal value of this function and where does it occur?
- (e) Calculate the gradient $\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \end{bmatrix}^T$.
- (f) When $\nabla f = 0$, what are the values of x and y?
- 3. In this question, we will explore some basic properties of the gradient.

Note: In this class, we use the following conventions:

- x represents a scalar
- X represents a random variable
- x represents a vector
- X represents a matrix or a random vector (context will tell)
- (a) Determine the derivative of $f(x) = a_0 + a_1 x$ and gradient of $g(x_1, x_2) = a_0 + a_1 x_1 + a_2 x_2$.

(b) Suppose
$$\mathbf{x} = \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix}^T$$
, and $h(\mathbf{x}) = \mathbf{a}^T \mathbf{x}$, where $\mathbf{a}, \mathbf{x} \in \mathbb{R}^n$. Determine ∇h .

(c) Determine the gradient of $f(\mathbf{x}) = \mathbf{x}^T \mathbf{x}$. (*Hint:* f is a scalar-valued function. How can you write $\mathbf{x}^T \mathbf{x}$ as a sum of scalars?)